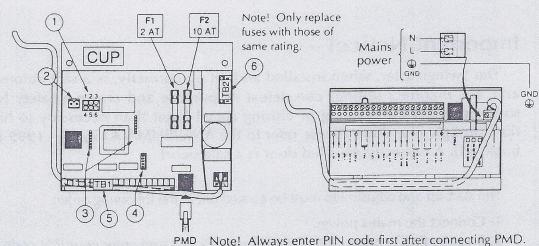
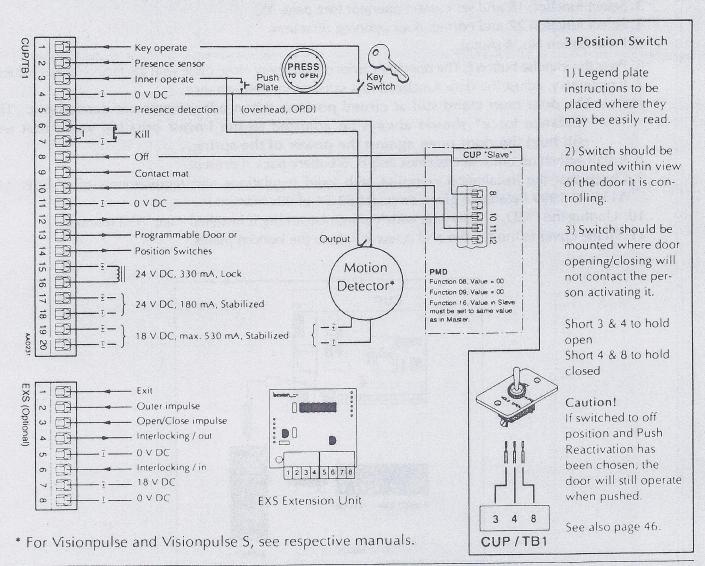
## Wiring The CUP Control Unit

- ① Cam/Switch cable connector
- ② Connector for motor cable
- ③ Connecters for EXS extension unit
- ④ Connector for revolution counter cable
- ⑤ TB1 Terminal block for external wiring
- © TB2 Terminal block for backup battery, EUS





# Adjusting The CUP Control Unit

#### Important Notice!

The Swingmaster, when installed and set up correctly, is a safe automatic power door operator, but incorrect settings can defeat its purpose and create a safety hazard. For safety reasons, never set the opening or closing speed faster than necessary to handle the traffic situation through your door. Please refer to the ANSI/BHMA A156.10 - 1999 excerpt in this manual (page 53). A correctly adjusted door is a safe door!

The start-up and adjustment must be carried out in the following order:

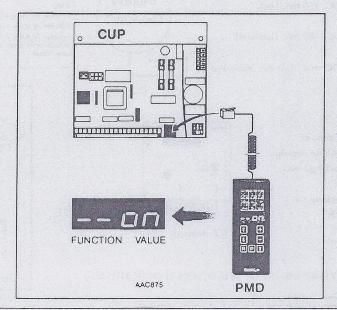
- 1. Connect the mains power.
- 2. Plug the PMD contact into the CUP control unit and enter your PIN code (see page 41).

Note! The PMD is not ready for use until a status or error code is displayed.

- 3. Select function 15 and set correct operator (see page 45).
- 4. Select function 27 and correct door opening direction.
- 5. Press button No. 4 (Auto).
- 6. Press the impulse button I. The operator carries out an open/ close cycle with the factory preset values.
- 7. If necessary, adjust the door functions to a satisfactory performance.

Note! The door must stand still at closed position when adjustments are carried out. The "balance force" should always be adjusted to the lowest possible value that will still hold the door open against the power of the spring.

- 8. Install activation units, accessories and EUS battery pack if present.
- 9. Check that the installation complies with valid regulations and requirements of ANSI/BHMA A156.10-1999 (reference given on pages 53-54 of this manual.)
- 10. Unplug the PMD, or continue with Visionpulse tuning if installed see VP-S manual.
- 11. Fit the cover to the header and screw it tight to the bottom plates.



### Introduction To PMD

The programming module PMD is used to program the operating values into the control units.

The PMD has a limited service life. A countdown is made at every connection and the remaining "value" is shown on the display. When the figures "-- 71" are shown, the PMD is unusable and must be updated.

#### PMD models:

PMD-B Service life: 2000 connections. PMD-C Service life: 400 connections.

PMD-E Customer version with restricted use. Service life: 400 connections.

#### PIN-code

All new or updated PMDs are factory pre-programmed with the PIN-code "1234".

- 1. Connect the PMD to the control unit.
- 2. "Pin " with a flashing dash will be shown on the display.
- 3. Enter the code "1234". Every entered digit will be indicated with a dash "\_" on the display.

Note! After five unsuccessful attempts to enter the correct PIN-code the error code "71" will be displayed. This means that the PMD is unusable and must be returned to the factory to be updated.

- 4. Push the button "P".
- 5. The display will consecutively show:
- a) Type of control unit e.g. CUD or CUP.
- b) Remaining "value" of the service life.
- c) "00".
- d) Actual status or error code e.g. "on".

Note: If status code 10 is displayed for swing doors, check that the correct operator type has been selected under function 15.

#### Change of PIN-code

The factory pre-programmed PIN-code can be changed to a personal code as follows:

- 1. Carry out the instructions 1-5 under "PIN-code" above.
- 2. Select function "30", value "b".
- 3. Push the button "P".
- 4. The display will show four flashing dashes "\_\_\_\_".
- 5. Enter your personal code (four digits). Every entered digit will be shown on the display.

Note! If a wrong digit is entered, disconnect and reconnect the PMD contact and start from the beginning with the factory pre-programmed PIN-code.

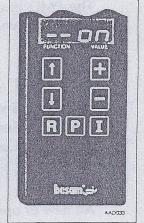
- 6. Push the button "P".
- 7. "Pin\_" with a flashing dash will be shown on the display.
- 8. Enter your "personal code" and push "P" once more to confirm that the correct code was entered.

Note! It is not possible to revert to old codes if you have forgotten the new one. If a mistake was made during the programming the PMD will revert to step 4 ("\_ \_ \_ \_").

### Function buttons

These buttons are used to set or check\* the functions (01-99) for speed, hold open time, monitoring, and so on. The up and down arrow buttons increase and decrease the number by one digit. If the button is held down for more than 1 second, the function number will be increased/decreased every 0.1 second. When the final function (99) has been reached, the digits will roll over to function 01 and start again.

\* Note! When selecting any of these functions, the last value programmed into the Swingmaster control unit will be displayed, except for function 99, where value 01 will always be displayed.



#### Value buttons

These buttons are used to set the value for the selected function. The plus and minus buttons increase and decrease the value by one digit. If the button is held down for more than 1 second, the value will be increased/decreased every 0.1 second. When the end value has been reached the digits will roll over and start again.

#### Program button

This button is used to program the control unit with the function and value selected on the PMD. To indicate that data have been transferred into the control unit, the display will be blank (fractions of a second) and then show the selected digits.

#### Impulse button

This button is used to give an opening impulse to the operator. If the button is held down, an impulse is given every 0.2 seconds.

#### Reset button

This button is used to reset the control unit. Hold the button down for about 2 seconds to reset.

#### Function display

When a FUNCTION button is depressed, the latest function used will be presented on the function display. If no function has been selected previously, the function "01" will be shown. If the FUNCTION and VALUE buttons are not activated for 5 s, the display will show "-".

#### Value display

The VALUE display shows the value for the selected function. If the FUNCTION and VALUE buttons are not activated for 5 s, the VALUE display will show the present status or error code for the operator.

#### Back

The function description on the back of the PMD is reversible. The green side is to be used when adjusting sliding doors and the blue side when adjusting swing doors.

#### Program selector (blue push-button set to be used)

Buttons 1-4 control necessary functions of the operator. The PMD will override the settings of the program selector, if installed. The program selector will resume function about 30 seconds after the PMD is removed.

#### Settings

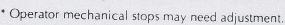
1.	o⊷o "Off"	The door is closed.
2.	"Exit"	Exit only.
3.	"Open"	The door is permanently open.
4.	"Auto"	The door opens with inner and outer activation units.
5.	Mat	Mat safety impulse.

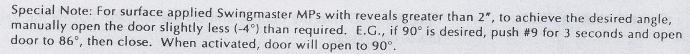
6. VP (IFD) Presence detection.

7. "Key impulse" Key opening impulse.

8. "Low speed Push the button for 3 s. The door opening" or opens with pre-set low speed. Used to "Learn" if VP-S automatically adjust the sensitivity of is connected the VP-S.

9. "Door opening Push the button for 3 s, then open the door to the required angle and close it angle >990" \* by hand. The new angle is now programmed into the control unit.





#### Pre-programmed run programs (Function 98)

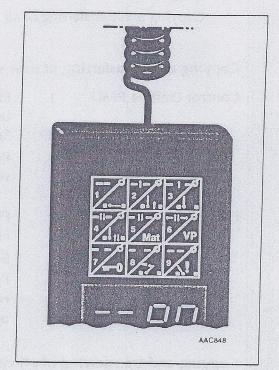
Pre-programmed basic values for six different run programs (operating performance) can be selected with the function 98 and any of the values from 01 to 06. The value 98/03 is factory pre-programmed and selected to give a satisfactory function for most doors.

When selecting the values in the order from 01 to 06, the performance of the operator is gradually increased and can be adapted to the valid operating conditions. If the performance has to be increased depending on door size and/or door weight, never use a higher value than necessary. To comply with authority requirements, the value selected must give the operator a smooth and safe closing.

#### Programming the run programs into the control unit

- Plug the PMD into the control unit on the operator.
- Select function 98 and any of the values from 01 to 06.
- 3. Press the program button P within 5 seconds. The selected run program will now be transferred from the PMD to the control unit.

Note! The only values transferred will be values that affect the operator performance.



#### Copying and transferring of programmed values (Function 98)

This function is used to facilitate the adjustment by copying and transferring the values from one smoothly running operator to another one with similar operating conditions. The values can be copied and transferred in two levels.

- Copying and transferring of user values only Functions 01–27.
- · Copying and transferring of all values.

#### Copying and transferring of user values only:

#### Control Unit → PMD

- 1. Plug the PMD into the control unit on the operator having the values to be copied.
- 2. Select function 98 and value 99.
- 3. Press the program button P within 5 seconds. The user values only will now be transferred from the control unit to the PMD.

#### PMD → Control Unit

- 1. Plug the PMD into the control unit on the operator receiving the copied values.
- 2. Select function 98 and value 98
- 3. Press the program button P within 5 seconds. The user values will now be transferred from the PMD to the control unit on the new operator.

#### Copying and transferring of all values:

#### Control Unit → PMD

- Plug the PMD into the control unit on the operator having the values to be copied.
- 2. Select function 98 and value 97.
- 3. Press the program button P within 5 seconds. All programmed values will now be transferred from the control unit to the PMD.

#### PMD → Control Unit

- 1. Plug the PMD into the control unit on the operator receiving the copied values.
- 2. Select function 98 and value 96.
- 3. Press the program button P within 5 seconds. All values will now be transferred from the PMD to the control unit on the new operator

### PMD – Functions And Values

01       High speed opening       15-90 %s         02       Low speed opening       05-15 %s         03       Low speed distance opening       05-40 °         04       High speed closing       15-60 %s         05       Low speed distance closing       05-15 %s         06       Low speed distance closing       05-30 °         07       Lock kick, additional       00-40 %s         08       Hold open time       00-60 s         09       Key open time       00-60 s         10       Door opening angle ¹       30-99 °         11       Switch 1, angle ²       00-99°         12       Switch 2, angle ²       00-99°         13       VP-S swing side ³       A/b no/yes         14       VP-S approach side ³       A/b no/yes         15       Type of operator ⁴       00-99         16       Push Reactivation, PR ⁵       00-60 s         17       Presence impulse monitoring ⁶       00-20         18       Mat safety monitoring ⁶       00-20         19       Presence detection type, break/make impulse ³       A/b no/yes         21       Navig-Aider (SA/OHC)       00-01         22       Balance force, open door       00-4	45 10 20 25 10 20 00 05 05 70 10 60
03Low speed distance opening05-40°04High speed closing15-60°/s05Low speed closing05-15°/s06Low speed distance closing05-30°07Lock kick, additional00-40°/s08Hold open time00-60 s09Key open time00-60 s10Door opening angle ¹30-99°11Switch 1, angle ²00-99°12Switch 2, angle ²00-99°13VP-S swing side ³A/b no/yes14VP-S approach side ³A/b no/yes15Type of operator ⁴00-9916Push Reactivation, PR ⁵00-60 s17Presence impulse monitoring 600-2018Mat safety monitoring 600-2019Presence detection type, break/make impulse 7A/b break/make20Overhead presence detectionA/b no/yes21Navig-Aider (SA/OHC)00-0122Balance force, open door00-4023Hold force, closed door 800-4024Locking without/with power 9A/b w/o / w.	20 25 10 20 00 05 05 70
15-60 °/s 05 Low speed closing 05 Low speed distance closing 06 Low speed distance closing 07 Lock kick, additional 00-40 °/s 08 Hold open time 09 Key open time 00-60 s 10 Door opening angle ¹ 30-99 ° 11 Switch 1, angle ² 00-99° 12 Switch 2, angle ² 00-99° 13 VP-S swing side ³ VP-S approach side ³ A/b no/yes 14 VP-S approach side ³ A/b no/yes 15 Type of operator ⁴ 00-99 16 Push Reactivation, PR ⁵ 00-60 s 17 Presence impulse monitoring 6 00-20 18 Mat safety monitoring 6 00-20 19 Presence detection type, break/make impulse 7 A/b break/make 20 Overhead presence detection A/b no/yes 21 Navig-Aider (SA/OHC) 22 Balance force, open door 23 Hold force, closed door 8 00-40 24 Locking without/with power 9 A/b w/o / w.	25 10 20 00 05 05 70
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07 Lock kick, additional 00-40 °/s  08 Hold open time 00-60 s  09 Key open time 00-60 s  10 Door opening angle ¹ 30-99 °  11 Switch 1, angle ² 00-99°  12 Switch 2, angle ² 00-99°  13 VP-S swing side ³ A/b no/yes  14 VP-S approach side ³ A/b no/yes  15 Type of operator ⁴ 00-99  16 Push Reactivation, PR ⁵ 00-60 s  17 Presence impulse monitoring 6 00-20  18 Mat safety monitoring 6 00-20  19 Presence detection type, break/make impulse 7 A/b break/make  20 Overhead presence detection A/b no/yes  21 Navig-Aider (SA/OHC) 00-01  22 Balance force, open door 00-40  23 Hold force, closed door 8 00-40  24 Locking without/with power 9 A/b w/o / w.	00 05 05 70 10
08Hold open time00-60 s09Key open time00-60 s10Door opening angle 130-99 °11Switch 1, angle 200-99°12Switch 2, angle 200-99°13VP-S swing side 3A/b no/yes14VP-S approach side 3A/b no/yes15Type of operator 400-9916Push Reactivation, PR 500-60 s17Presence impulse monitoring 600-2018Mat safety monitoring 600-2019Presence detection type, break/make impulse 7A/b break/make20Overhead presence detectionA/b no/yes21Navig-Aider (SA/OHC)00-0122Balance force, open door00-4023Hold force, closed door 800-4024Locking without/with power 9A/b w/o / w.	05 05 70 10
09Key open time00-60 s10Door opening angle 130-99 °11Switch 1, angle 200-99°12Switch 2, angle 200-99°13VP-S swing side 3A/b no/yes14VP-S approach side 3A/b no/yes15Type of operator 400-9916Push Reactivation, PR 500-60 s17Presence impulse monitoring 600-2018Mat safety monitoring 600-2019Presence detection type, break/make impulse 7A/b break/make20Overhead presence detectionA/b no/yes21Navig-Aider (SA/OHC)00-0122Balance force, open door00-4023Hold force, closed door 800-4024Locking without/with power 9A/b w/o / w.	05 70 10
10 Door opening angle <sup>1</sup> 30-99 °  11 Switch 1, angle <sup>2</sup> 00-99°  12 Switch 2, angle <sup>2</sup> 00-99°  13 VP-S swing side <sup>3</sup> A/b no/yes  14 VP-S approach side <sup>3</sup> A/b no/yes  15 Type of operator <sup>4</sup> 00-99  16 Push Reactivation, PR <sup>5</sup> 00-60 s  17 Presence impulse monitoring <sup>6</sup> 00-20  18 Mat safety monitoring <sup>6</sup> 00-20  19 Presence detection type, break/make impulse <sup>7</sup> A/b break/make  20 Overhead presence detection A/b no/yes  21 Navig-Aider (SA/OHC) 00-01  22 Balance force, open door  23 Hold force, closed door <sup>8</sup> 00-40  24 Locking without/with power <sup>9</sup> A/b w/o / w.	70
11 Switch 1, angle 2 00-99° 12 Switch 2, angle 2 00-99° 13 VP-S swing side 3 A/b no/yes 14 VP-S approach side 3 A/b no/yes 15 Type of operator 4 00-99 16 Push Reactivation, PR 5 00-60 s 17 Presence impulse monitoring 6 00-20 18 Mat safety monitoring 6 00-20 19 Presence detection type, break/make impulse 7 A/b break/make 20 Overhead presence detection A/b no/yes 21 Navig-Aider (SA/OHC) 00-01 22 Balance force, open door 00-40 23 Hold force, closed door 8 00-40 24 Locking without/with power 9 A/b w/o / w.	10
12 Switch 2, angle 2 00-99°  13 VP-S swing side 3 A/b no/yes 14 VP-S approach side 3 A/b no/yes 15 Type of operator 4 00-99  16 Push Reactivation, PR 5 00-60 s  17 Presence impulse monitoring 6 00-20  18 Mat safety monitoring 6 00-20  19 Presence detection type, break/make impulse 7 A/b break/make 20 Overhead presence detection A/b no/yes 21 Navig-Aider (SA/OHC) 00-01  22 Balance force, open door 00-40 23 Hold force, closed door 8 00-40  24 Locking without/with power 9 A/b w/o / w.	
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14 VP-S approach side <sup>3</sup> A/b no/yes  15 Type of operator <sup>4</sup> 00-99  16 Push Reactivation, PR <sup>5</sup> 00-60 s  17 Presence impulse monitoring <sup>6</sup> 00-20  18 Mat safety monitoring <sup>6</sup> 00-20  19 Presence detection type, break/make impulse <sup>7</sup> A/b break/make  20 Overhead presence detection A/b no/yes  21 Navig-Aider (SA/OHC) 00-01  22 Balance force, open door 00-40  23 Hold force, closed door <sup>8</sup> 00-40  24 Locking without/with power <sup>9</sup> A/b w/o / w.	
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17 Presence impulse monitoring 6 00-20 18 Mat safety monitoring 6 00-20 19 Presence detection type, break/make impulse 7 A/b break/make 20 Overhead presence detection A/b no/yes 21 Navig-Aider (SA/OHC) 00-01 22 Balance force, open door 00-40 23 Hold force, closed door 8 00-40 24 Locking without/with power 9 A/b w/o / w.	00
18 Mat safety monitoring 6 00-20  19 Presence detection type, break/make impulse 7 A/b break/make  20 Overhead presence detection A/b no/yes  21 Navig-Aider (SA/OHC) 00-01  22 Balance force, open door 00-40  23 Hold force, closed door 8 00-40  24 Locking without/with power 9 A/b w/o / w.	02
18 Mat safety monitoring 6 00-20  19 Presence detection type, break/make impulse 7 A/b break/make  20 Overhead presence detection A/b no/yes  21 Navig-Aider (SA/OHC) 00-01  22 Balance force, open door 00-40  23 Hold force, closed door 8 00-40  24 Locking without/with power 9 A/b w/o / w.	20
20 Overhead presence detection A/b no/yes 21 Navig-Aider (SA/OHC) 00-01 22 Balance force, open door 23 Hold force, closed door 8 00-40 24 Locking without/with power 9 A/b w/o / w.	20
21 Navig-Aider (SA/OHC)  22 Balance force, open door 23 Hold force, closed door <sup>8</sup> 24 Locking without/with power <sup>9</sup> A/b w/o / w.	Ь
22 Balance force, open door 23 Hold force, closed door <sup>8</sup> 00-40  24 Locking without/with power <sup>9</sup> A/b w/o / w.	Α
23 Hold force, closed door <sup>8</sup> 00-40  24 Locking without/with power <sup>9</sup> A/b w/o / w.	00
24 Locking without/with power <sup>9</sup> A/b w/o / w.	24
	00
Opening delay for unlocking 10 00-50 x 0,1 s	Α
	00
26 Spring closing only A/b no/yes	A
27 Door opening direction A/b	A
Number of operator cycles performed x 10000 00-99	00
Number of operator cycles performed x 100 00-99	00
30 Change of PIN-code <sup>11</sup> A/b no/yes	Α
96 VP-S swing side, status <sup>3</sup> -9 → .9	.F
97 VP-S approach side, status <sup>3</sup> -9→.9	.F
98 Run program <sup>12</sup> 01-06	03
Copying and transferring of values between operators 13 96-99	_
99 System tests <sup>14</sup> 01-05	

- \*) Factory pre-programmed values in the control unit.
- 1) To set angle >99°, see item 9, page 43.
- 2) Used for switching of the VP (IFD) detection fields.
- 3) Used if VP-S is installed on swing/approach side.
- 4) IK-A= 00; IKA-S=02
- 5) Value 00 = No PR. 01-60 s = Hold open time.
- 6) Value 00 = No monitoring, 01-20 = Monitoring. The control unit will monitor the VP-S (IFD) and/or the mat. After the set value of actuations (01-20) without a VP-S (IFD) /mat impulse, the door will stay open. Note: for trained traffic applications with no presence detection, this may be set to 00.
- 7) Used for switching between break or make impulse for terminal No. 5 on the CUP.
- 8) Selects an additional hold force for a closed door.
- 9) After changing always press the reset button R.
- 10) An impulsed operator signals a lock-release to unlock the striking plate.
- 11) See page 41.
- 12) Pre-programmed basic values for 6 different run programs can be selected (see page 43).
- 13) See page 44.
- 14) 5 functional tests can be performed (see page 52).

# PMD Codes, Tests and Status

# PMD error codes.

Note that if more than one error code exists, correcting the first will let the second display, correcting the second will let the third display, and so on until all errors codes have been fixed.

# Testing with the PMD.

The PMD can initiate some system tests. Select function 99 and then enter the values shown below to specify a particular test. Press the program button P on the PMD to start the test. If the test is unsuccessful an error code will flash on the value display.

# Status codes with the PMD.

The PMD normally shows the following status codes during operation. These status codes are not error codes. If any one of the status codes are constantly displayed during cycling, the corresponding input device has to be checked, and if necessary remedied or replaced.

# Note!

If the fault persists and all the recommended measures have been taken, the operator and control must be returned well packed to the factory. Please include a written description of the problem with the unit being returned.

<b>Value</b> 01 02	Test Of  External program selector switch  Motor, Visual test. (Let the door close before commencing this test.)	Test Of  External program selector switch  S1 flashing  Motor, Visual test. (Let the door close before The motor runs about 1 second in the opening commencing this test.)
03 04 05	Revolution counter Mat safety monitoring Presence impulse monitoring	54 flashing 51 flashing 52 flashing

Remedies  Normal – everything is OK. Let the door finish its cycle. Check this input.	Let the door finish its cycle. Close the door with new impulse.
Status Operation ok Search for closed position Inner impulse active Outer impulse active Key impulse active Synchronizing impulse active Interlocking impulse active Anat safety active Presence detection active Presence impulse active Rill impulse active Coor blocked Kill impulse active	Low speed opening/Learn Door opened with open/close impulse
Status Code on 10 11 12 13 14 15 16 17 18	22